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ECE560: Computer Systems Performance Evaluation

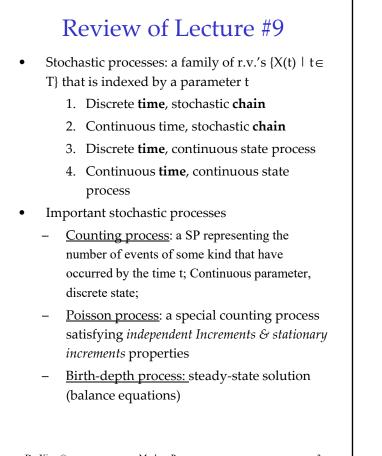


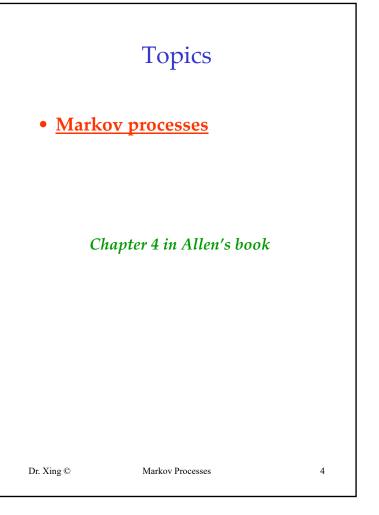
Lecture #10 – Markov Processes

Instructor: Dr. Liudong Xing Spring 2024

Administration Issues (2/21, Wed.)

- Homework #3
 - Due: Today
- Project proposal (refer to Guidelines)
 Due: February 23, Friday
- Today's topics
 - Finish L#9 (birth-death process)
 - Then L#10 (Markov process)





Markov Processes

Markov Processes

A stochastic process is a Markov process *iff* probabilities of future states depend only on

the current state and not on how it reached that state

i.e., all influences of the past on the system's future is contained in the current state.

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Markov Processes

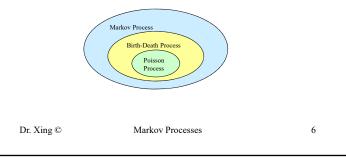
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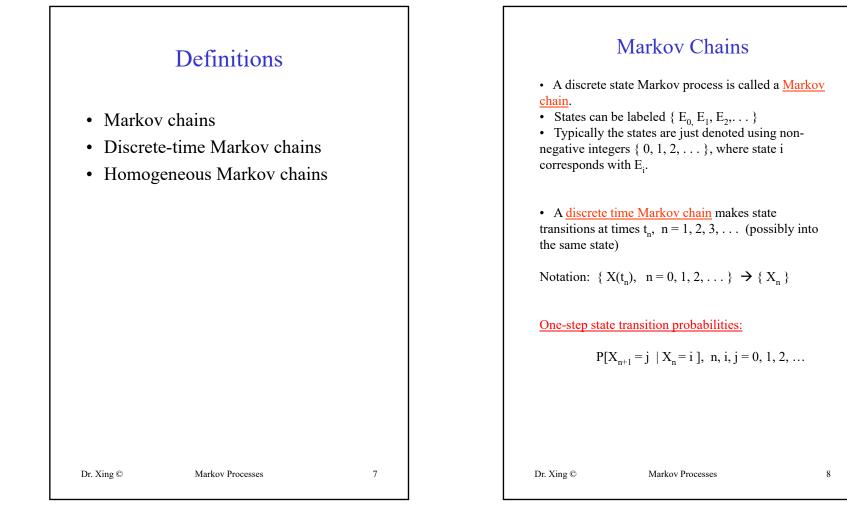
Formal Definition

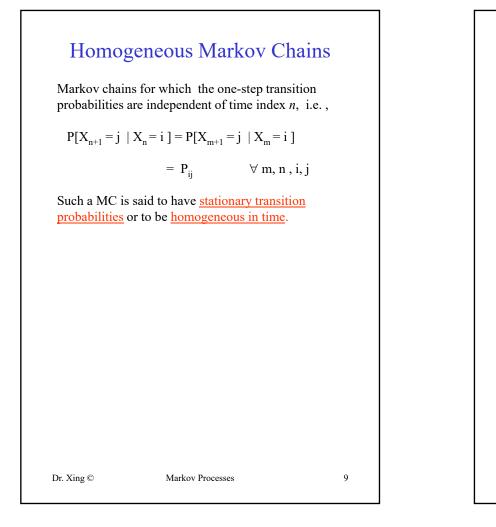
A stochastic process {X(t), $t \in T$ } is a Markov process if for any set of n + 1 values $t_1 < t_2 < .$ $.. < t_n < t_{n+1}$ in the index set T and any set of n+1 states { $x_1, x_2, ..., x_n, x_{n+1}$ }

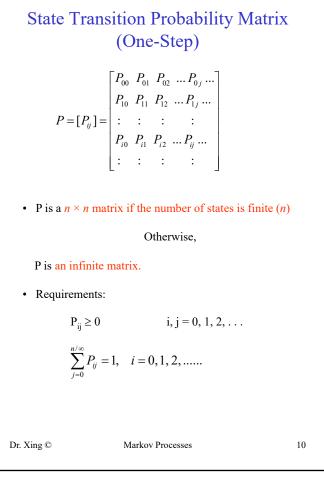
 $P[X(t_{n+1}) = x_{n+1} | X(t_1) = x_1, X(t_2) = x_2, ... X(t_n) = x_n]$ $\equiv P[X(t_{n+1}) = x_{n+1} | X(t_n) = x_n]$

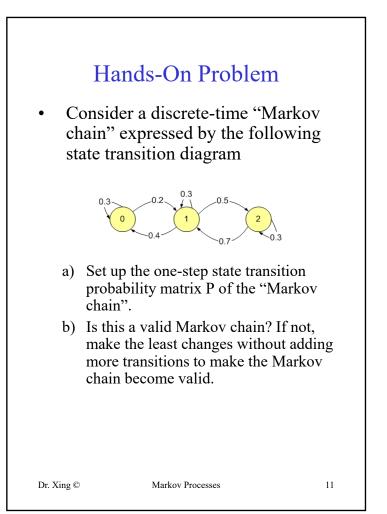
Note: All birth-and-death processes are Markov Processes. Hence, the Poisson process is a Markov Process











Discrete-Time MC: Example I

- Consider a sequence of Bernoulli trials, for each trial
 - Success probability is *p*
 - Failure probability is q = l p

Assume X_n -- the state of the process at trial n, is the number of uninterrupted successes that have been completed at this point, i.e., the length of consecutive successes.

Find the state transition probability matrix and state transition diagram.

Trial : F S S F F S S S F n = 0 1 2 3 4 5 6 7 8 X_n =

Markov Processes

State Transition Probability Matrix (*n*-Step)

• *n*-step transition probabilities

$$P_{ij}^{(n)} = P[X_n = j \mid X_0 = i]$$

For homogeneous MC

 $P_{ij}^{(1)} = P_{ij}$

$$P_{ij}^{(n)} = P[X_{m+n} = j \mid X_m = i], \quad \forall m \ge 0, n > 0$$

And

$$P_{ij}^{(0)} = \delta_{ij} = \begin{cases} 1 \text{ if } i = j \\ 0 \text{ if } i \neq j \end{cases}$$
 Kronecker Delta function

• Denote the matrix of *n*-step transition probabilities by

$$P^{(n)} = [P_{ii}^{(n)}]$$

Then

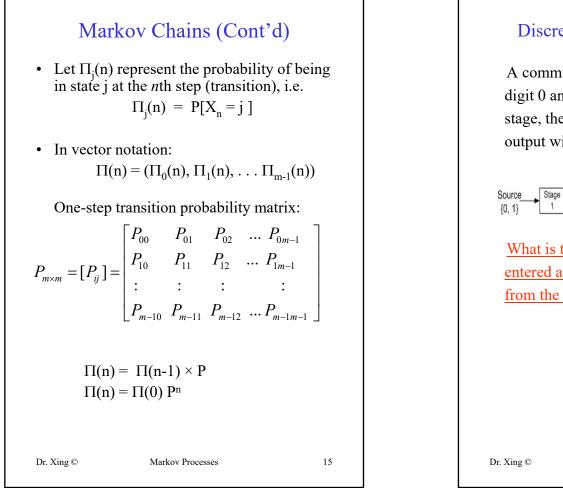
$$P^{(n)} = P^{(n-1)}P = P^n$$

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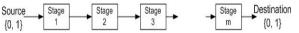
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State Transition Probability Matrix (*n*-Step) (Proof) • Why $P^{(n)} = P^{(n-1)}P = P^n$? $P_{ii}^{(n+m)} = P\{X_{n+m} = j | X_0 = i\}$ $= \sum_{k=0}^{\infty} P\{X_{n+m} = j, X_n = k | X_0 = i\}$ $=\sum_{k=0}^{\infty} P\{X_{n+m} = j | X_n = k, X_0 = i\} P\{X_n = k | X_0 = i\}$ $=\sum_{k=0}^{\infty}P_{ik}^{(n)}P_{kj}^{(m)}\qquad \forall n,m,i,j\geq 0$ -- Chapman-Kolmogorov equations In particular, when m=1 $P_{ij}^{(n+1)} = \sum_{k=0}^{\infty} P_{ik}^{(n)} P_{kj} \qquad n = 1, 2, \dots, \ \forall i, j \ge 0$ *i.e.*, $P_{ij}^{(n)} = \sum_{k=0}^{\infty} P_{ik}^{(n-1)} P_{kj}$ $n = 2, 3, ..., \forall i, j \ge 0$ $P^{(n)} = [P_{ii}^{(n)}] \implies P^{(n)} = P^{(n-1)}P = P^n$ Dr. Xing © Markov Processes 14



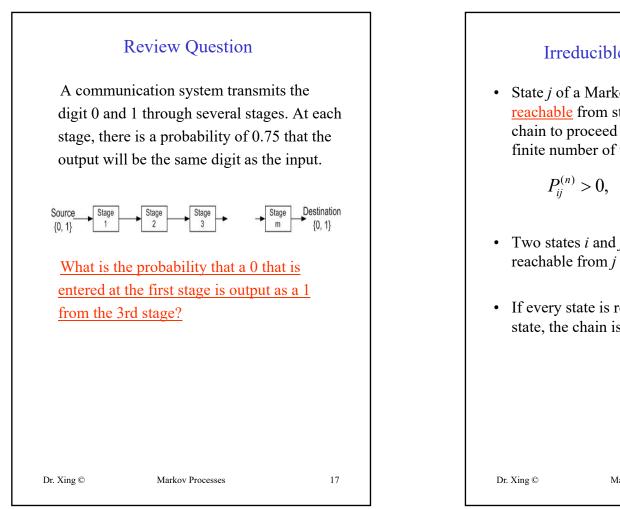
Discrete-Time MC: Example II

A communication system transmits the digit 0 and 1 through several stages. At each stage, there is a probability of 0.75 that the output will be the same digit as the input.



What is the probability that a 0 that is entered at the first stage is output as a 0 from the 4th stage?

Markov Processes



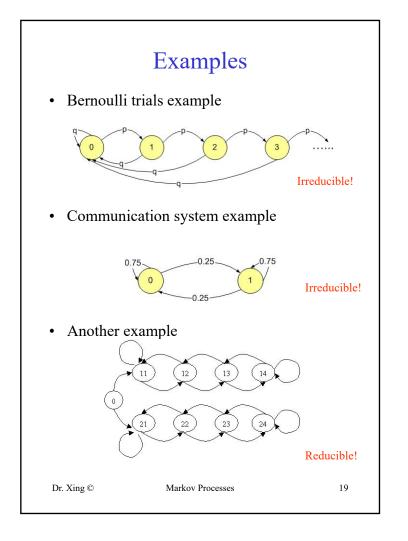
Irreducible Markov Chains

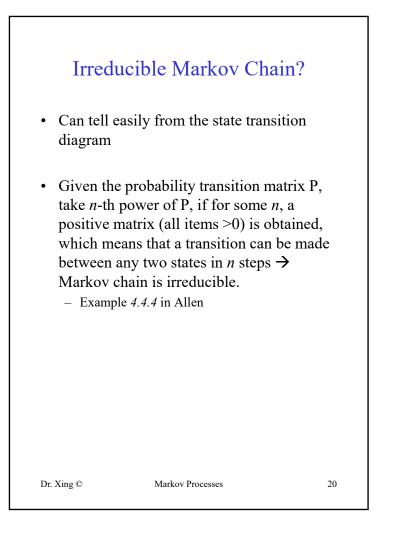
• State *j* of a Markov chain {X_n} is said to be <u>reachable</u> from state *i* if it is possible for the chain to proceed from state *i* to state *j* in a finite number of transitions, i.e.

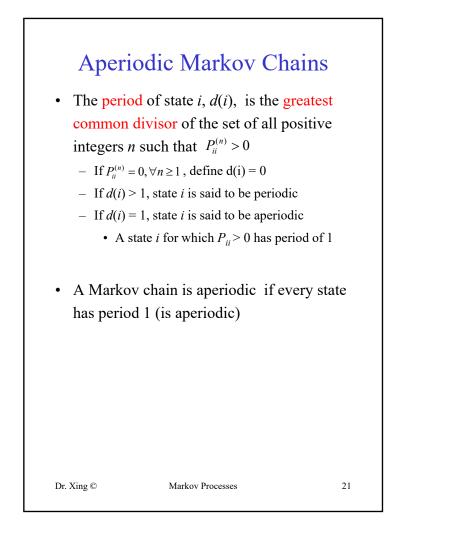
 $P_{ij}^{(n)} > 0$, for some $n \ge 0$

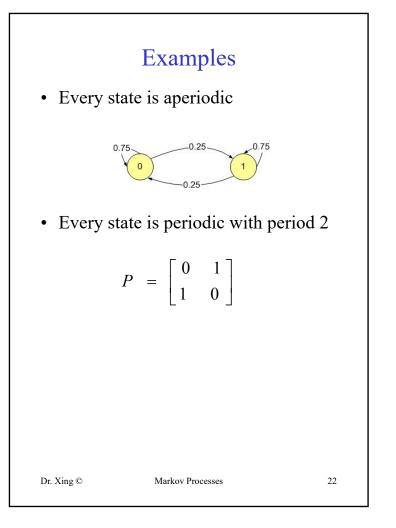
- Two states *i* and *j* are to <u>communicate</u> if *i* is reachable from *j* and *j* is reachable from *i*.
- If every state is reachable from every other state, the chain is said to be <u>irreducible</u>.

Markov Processes









Recurrent Markov Chains

• For each state *i*, define $f_i^{(n)}$ to be the probability that the first return to state *i* occurs, *n* steps (transitions) after leaving *i*, i.e.,

$$f_i^{(n)} = P[X_n = i, X_k \neq i \text{ for } k = 1, 2, ..., n-1 | X_0 = i]$$

Define: $f_i^{(0)} = 1, \forall i$

Then, the probability of ever returning to state *i* is given by $f_i = \sum_{n=1}^{\infty} f_i^{(n)}$

- If $f_i < 1$, then state *i* is a <u>transient</u> state
- If $f_i = 1$, then state *i* is a <u>recurrent</u> state
 - Mean recurrence time of *i*, i.e., the average time (steps) to return to state *i* is

$$m_i = \sum_{n=1}^{\infty} n f_i^{(n)}$$

- If $m_i = \infty$, state *i* is said to be *recurrent null*
- If $m_i < \infty$, state *i* is said to be *positive recurrent* or recurrent non-null.

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Ergodic Markov Chains

- A discrete-time Markov chain is said to be **ergodic** if it is
 - <u>irreducible</u>: you can get from every state to every other
 - <u>aperiodic</u>: every state has period 1. For each state there are paths back to that state of various lengths, i.e., not all multiples of the same integer k>1.
 - for which all states are positive recurrent: for each state, upon leaving the state you will return with probability 1 and within a finite mean time.

A finite-state Markov chain that is irreducible and aperiodic is ergodic.

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- Let Π_j(n) represent the probability that discrete time Markov chain {X_n} is in state j at the nth step (transition), i.e. Π_j(n) = P[X_n = j]
- Initial distribution of state *j* is $\Pi_j(0) = P[X_0 = j], j=0,1,...$
- A discrete Markov chain is said to have a *stationary probability distribution* $\Pi = (\Pi_0, \Pi_1, \Pi_2, ...)$ if

$$- \Pi_j(0) = \Pi_j(n) = \Pi_j, \quad \forall_j \quad \forall_j$$

– Equivalently, the matrix equation $\Pi = \Pi^* P$ is satisfied.

- Requirements

 $\Pi_i \ge 0 \quad \forall_i \text{ and } \sum_i \Pi_i = 1$

• A Markov chain is said to have a *long-run* or *limiting probability distribution* $\Pi = (\Pi_0, \Pi_1, \Pi_2, ...)$ if

$$\lim_{n\to\infty}\Pi_j(n) = \lim_{n\to\infty}P[X_n = j] = \Pi_j, j = 0,1,\dots$$

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Properties of Ergodic MC

• The limiting probabilities

 $\lim_{n \to \infty} \Pi_{j}(n) = \Pi_{j}, j = 0, 1, \dots$

always exist and are independent of the initial state distribution $\Pi(0) = (\Pi_0(0), \Pi_1(0), \Pi_2(0), \ldots)$.

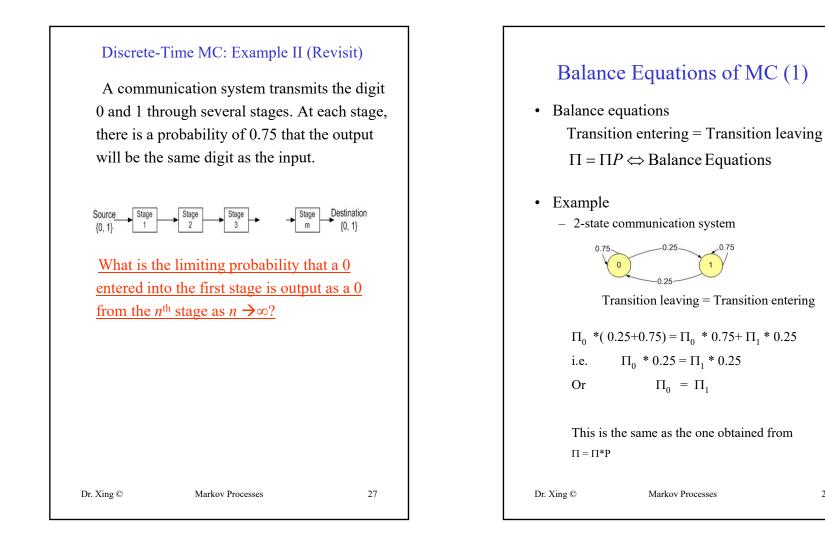
- $\Pi = (\Pi_0, \Pi_1, \Pi_2, ...)$ forms a stationary probability distribution and $\Pi_i = 1 / m_i$.
- The limiting distribution is the unique solution to the equations

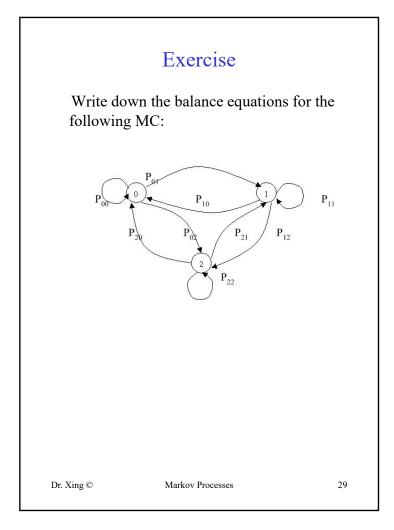
 $\Pi = \Pi^* P$ and $\sum_i \Pi_i = 1$

 Stationary probability distribution = Long-run (limiting) probability distribution
 Also called "equilibrium" or "steady-state" distribution.

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Hands-On Problem

- Suppose that in New Zealand, home of the Gala apple, years for these wonderful apples can be described as *Great*, *Average*, or *Poor*. Suppose that following a *Great* year the probabilities of *Great*, *Average*, or *Poor* years are 0.5, 0.3, and 0.2, respectively. Suppose also that following an *Average* year the probabilities of *Great*, *Average*, or *Poor* years are 0.2, 0.5, and 0.3, respectively. Finally, suppose that following a *Poor* years are 0.2, 0.2, and 0.6, respectively. Assume we can describe the situation from year to year by a Markov chain with the states 0, 1, and 2 corresponding to *Great*, *Average*, and *Poor* years, respectively.
 - Set up the transition probability matrix P of the Markov chain & draw the state transition diagram.
 - Is the Markov chain ergodic? Why or why not?
 - Suppose the initial probability for a *Great* year is 0.2, for an *Average* year is 0.5, and for a *Poor* year is 0.3. What is the probability of a *Great* year <u>after one year</u>?
 - What is the probability for a *Great* year <u>after n</u> year as $n \rightarrow$ infinity?

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